NACHİ

POWER MEISTER

Power Meister



AC servo motor controls hydraulic pump speed and direction. Generate pressure and flow to match the operating cycle of machinery and to stop during idle times.

Incredible energy savings by only operating when necessary.

Also, position, speed, and pressure are controlled with great precision by using a high-speed digital processing servo controller.

Features

High power with 30MPa maximum pressure.

Designed so pump operates only when necessary for energy savings and low noise.

Great energy savings compared to conventional hydraulic systems.

High-speed processing of the servo controller makes positioning on the order of μ m possible.

Compact all-in-one design saves space.

(select either vertical or horizontal setup)

Principle of operation

Rotating the motor forward brings hydraulic fluid to the head side of the cylinder which lifts the cylinder. Reversing the motor pushes hydraulic fluid to the rod side and pushes the cylinder down. The direction the pump rotates controls the direction of the cylinder, and the speed of rotation controls the speed.



System Configuration (Standard Configuration)

Signals to operate the cylinder (position, speed, and pressure) are sent from the control equipment to the servo controller and the hydraulic unit responds according to the signals. The servo controller receives feedback from sensors and accurately controls the cylinder so the deviation from the signals is 0. A feedback system using position and pressure sensors makes it possible to accurately control position, speed, and thrust (pressure).

About Power Meister

- 1 Hydraulic unit (UPS)
- 2 Servo controller (EPD)
- ③Servo amp
 - (compatible with motor mounted on item (1))
- (4) Motor cable
- (select from 3, 5, or 10 meters)
- 5 Encoder cable
- (select from 3, 5, or 10 meters)
- (6) Cable to computer (3 m))
- It becomes offers.
- Note) Customers must provide piping, wiring, hydraulic cylinder, sensors, control panel, and other equipment. (Contact us for information about cylinders and sensors.)

Specifications

Hydraulic Unit

Motor	AC servo motor (0.5 to 7.5kW (servo amp drive)) Power supply 3-phase 200 to 230VAC, 50/60Hz (servo amp power supply)
Pump	Piston pump (2.0 to 15.8cm ³ /rev)
Operating Ambient Temperature/Humidity	0 to +40 $^\circ\!\!\!\!\!\!^{\circ}\!\!\!\!^{\circ}\!\!\!^{\circ}\!\!\!\!$ to 90%RH (non-condensation)
Temperature Range of Hydraulic Fluid (${}^{\circ}\!\!\!{}^{\circ}\!\!\!{}^{\circ}\!\!\!{}^{\circ}$	5 to 60 $^\circ\!\mathrm{C}$
Recommended Hydraulic Fluid	Wear resistant hydraulic fluid ISO VG32 to 68 (VG46 recommended)
Operating Viscosity Range	20 to 200mm ² /s {cSt}
Degree of Contamination	NAS 10 or better
Safety Valve Pressure Adjustment Range	3.5 to 30MPa
Maximum Working Pressure	30MPa (for hydraulic pump) (maximum operating pressure varies according to motor performance and options)
Color of Paint	Black

• UPS-00A

Model No.	Motor Output kW	Pump Capacity cm ³ /rev	Maximum RPM min ⁻¹ (Note 1)	Maximum Flow Rate & /min (Note 2)	Pressure Rating MPa (Continuous (Note 3))	Maximum Working Pressure MPa (Short term (Note 3))	Tank Size Lit. (nominal)	Hydraulic Fluid Level Range Lit. (estimate (Note 5))
UPS-00A-2*05	- 0.5	2.0	3000	6.0	6.7	10.0	V: 1.9	V: 0.6
UPS-00A-4*05		4.0		12.0	3.3	5.0	H: 1.5	H: 0.3
UPS-00A-2*10	- 1.0	2.0	3000	6.0	13.4	20.0	V: 1.9	V: 0.6
UPS-00A-4*10		4.0		12.0	6.7	10.0	H: 1.5	H: 0.3
UPS-00A-2*15	- 1.5	2.0	3000	6.0	20.0	30.0	V: 1.9	V: 0.6
UPS-00A-4*15		4.0	3000	12.0	10.0	15.0	H: 1.5	H: 0.3
UPS-00A-2*20	2.0	2.0	3000	6.0	25.4	30.0	V: 1.9	V: 0.6
UPS-00A-4*20		4.0		12.0	12.7	19.0	H: 1.5	H: 0.3

• UPS-0A

Model No.	Motor Output kW	Pump Capacity cm³/rev	Maximum RPM min ⁻¹ (Note 1)	Maximum Flow Rate & /min (Note 2)	Pressure Rating MPa (Continuous (Note 3))	Maximum Working Pressure MPa (Short term (Note 3))	Tank Size Lit. (nominal)	Hydraulic Fluid Level Range Lit. (estimate (Note 5))
UPS-0A-5*20	2.0	4.7	2500	11.7	11.2	16.8	3.0	V: 0.6 H: 0.4
UPS-0A-7*20		6.7		16.7	8.0	11.9		

• UPS-1A

Model No.	Motor Output kW	Pump Capacity cm³/rev	Maximum RPM min ⁻¹ (Note 1)	Maximum Flow Rate & /min (Note 2)	Pressure Rating MPa (Continuous (Note 3))	Maximum Working Pressure MPa (Short term (Note 3))	Tank Size Lit. (nominal)	Hydraulic Fluid Level Range Lit. (estimate (Note 5))
UPS-1A-11*29		11.0	2500	27.5	9.5	14.3	4.5	V: 1.2 H: 0.6
UPS-1A-13*29	2.9	12.9		32.2	8.1	12.2		
UPS-1A-16*29		15.8		39.5	6.6	10.0		
UPS-1A-11*44		11.0	2500	27.5	14.6	21.8	4.5	V: 1.2 H: 0.6
UPS-1A-13*44	4.4	12.9		32.2	12.4	18.6		
UPS-1A-16*44		15.8		39.5	10.1	15.2		
UPS-1A-11*55	5.5	11.0	2500	27.5	17.9	26.9	4.5	V: 1.2 H: 0.6 V: 1.2 H: 0.6
UPS-1A-13*55		12.9		32.2	15.3	22.9		
UPS-1A-16*55		15.8		39.5	12.5	18.7		
UPS-1A-11*75	7.5	11.0	2500	27.5	24.6	30.0	4.5	
UPS-1A-13*75		12.9		32.2	21.0	30.0		
UPS-1A-16*75		15.8		39.5	17.1	25.7		11. 0.0

Notes 1.) Operating pressure may be limited by maximum RPM depending on the motor output. Notes 2.) Theoretical flow under no load. Notes 3.) Rated pressure is (available) pressure at rated torque of motor, maximum operating pressure is pressure output at 150% torque. However, if this pressure exceeds 30MPa, the maximum operating pressure of the hydraulic unit is limited to below 30MPa. Notes 4.) Operating conditions may limit the maximum RPM and operating pressure to values lower than those shown in the table above, contact us for many information. more information.

Contact us about continuously adding pressure while operation is stopped. Notes 5.) An auxiliary tank can be connected if fluctuation in oil volume is greater than allowed values. Contact us for information on how to connect an auxiliary tank.

Servo Controller

Power Supply/Consumption		24VDC ±15%/less than 10W	Separate power supply for sensor is needed	
Operating Ambient Temperature/Humidity		0 to +55 \mathbb{C} /90% RH or less (no condensation)		
Controlled Parameters		Cylinder position, speed, pressure	Control mode automatic switching function available	
Command Command Input		Analog voltage DC ±10V/maximum cylinder speed (*1), cylinder extended by positive voltage, cylinder retracted by negative voltage	(*1) Parameter setting	
		Analog voltage DC ±10V/maximum control pressure (*2), positive voltage adds pressure to head side, negative voltage adds pressure to rod side	(*2) Trimmer setting	
	Position Command	Position selection contact signal (4 contacts), target position selected by bit pattern of 4 contacts, acceleration function generated in con- troller moves cylinder to target position	Target position, maximum speed, and acceleration set using internal parameters	
Input Signals (Contact Signals)		Servo on, alarm reset, control mode external switching, start point search start, start point retraction end point LS, start point proximity LS		
Output Signals		Alarm, servo ready, control mode monitor, start point search end/in position (also output), pressure consistency		
Pressure Sensor Input		Analog voltage 0.5 to 4.5V, or 1 to 5V (2ch)	Uses pressure sensor with response time of 1 ms or less.	
Position Sensor Input		90° phase difference biphasic pulse, start point pulse (line receiver input) or analog voltage 0 to 10V (only with -A option)	If using pulse output position sensor, start point search is necessary once after turning on the power Pulse output positioning sensor: Uses sensor with resolution of 1 μ m or less Analog voltage output positioning sensor: Uses sen- sor with response time of 2 ms or less	
Servo Amp I/F		Output: Motor revolve command (analog voltage ±10VDC), servo amp, servo alarm reset Input: Servo alarm, servo ready		

Connector for controller, pins are attached.

Servo Amp

Hydraulic Unit Model (UPS Series)	Motor Output kW	Compatible Servo Amp Model (According to Model Ordered)	Remarks
UPS-00A-*¥05	0.5	EPA-PD1-10-R050-8647B	Regenerative resistor built in, cable connector included
UPS-00A-*\10	1.0	EPA-PD1-10-R100-8647B	Regenerative resistor built in, cable connector included
UPS-00A-*¥15	1.5	EPA-PD1-10-R150-8647B	Regenerative resistor built in, cable connector included
UPS-00A-*¥20	2.0	EPA-PD1-10-R200-8647B	Regenerative resistor built in, cable connector included
UPS-0A-*¥20	2.0	EPA-PD1-10-R200-8647B	Regenerative resistor built in, cable connector included
UPS-1A-**¥29	2.9	EPA-PD1-10-YV290-8647B	Regenerative resistor built in (cable connector not included)
UPS-1A-**¥44	4.4	EPA-PD1-10-YV440-8647B	Regenerative resistor built in (cable connector not included)
UPS-1A-**¥55	5.5	EPA-PD1-10-R550-8647B	Regenerative resistor built in, cable connector included
UPS-1A-**¥75	7.5	EPA-PD1-10-R750-8647B	External regenerative resistor and cable connector included

Notes 1.) Power: 3-phase 200 to 230VAC, 50/60Hz

Notes 2.) Separate motor cable and encoder cable are needed to connect the servo motor on the hydraulic unit.

Notes 3.) An auxiliary external regenerative resistor may need to be added in some operating conditions if the built-in or external regenerative resistor is not sufficient. For more details contact us with information about your operating conditions (load motion diagram).







C and S and tank options H and S.

Note 2.) Does not include circuit or tank options or weight of hydraulic fluid. Note 3.) Install the air breather facing up.





Servo Amp for UPS-00A





Performance Characteristics

• Pressure Command Voltage - Pressure Characteristics (0 to 100%)



ind wave





Command 1Hz sine wave, amplitude 10 to 90%

 Dwelling Pressure - Power Consumption Characteristics Hydraulic unit (UPS)





• Speed Command Voltage - Speed Characteristics (0 to 100%)



(If oil motor is running as actuator)

Shape of command way

• Speed Sine Wave Response



Command 1Hz sine wave, amplitude 10 to 90% (If oil motor is running as actuator)